

Our paper on a Tomato Cluster Harvesting Robot won 2010 EAEF Best Paper Award

Our Paper entitled “Path Planning of Tomato Cluster Harvesting Robot for Realizing Low Vibration and Speedy Transportation” received 2010 EAEF Best Paper Award as below:



The paper is published through EAEF 2 (3), AABEA (CIAM, JSAM and KSAM).

http://www.jstage.jst.go.jp/browse/eaef/2/3/_contents

It is expected that research project on this and other projects will be further propelled based on this honorable achievement.