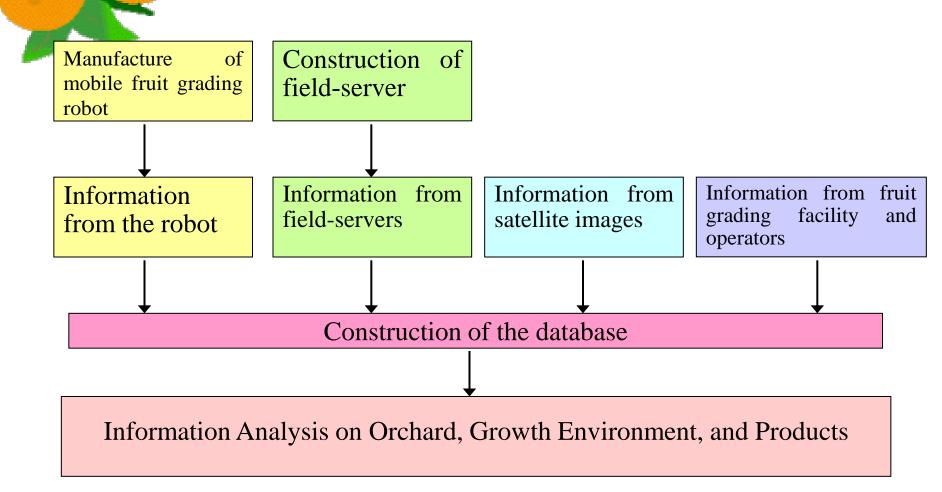
Precision citrus production concept based on information from mobile citrus fruit grading robot, field-server, and satellite

Ehime Agricultural Experiment Station
Yasushi KOHNO





Outline of the whole project

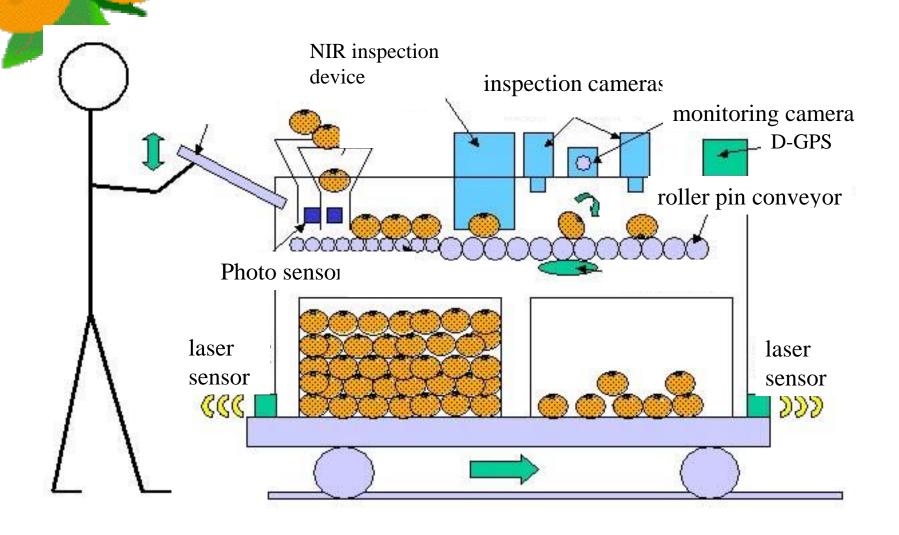


The aim of this study

- To clarify performance and accuracy of each device by multi-dimensional analysis with spatial consideration and time scale.
- ◆ To clarify required information for precise production of citrus fruit and performance and function of each sensor.
- ◆ To enable the database to be used for both tree management and food traceability to keep safety and security on food distribution.

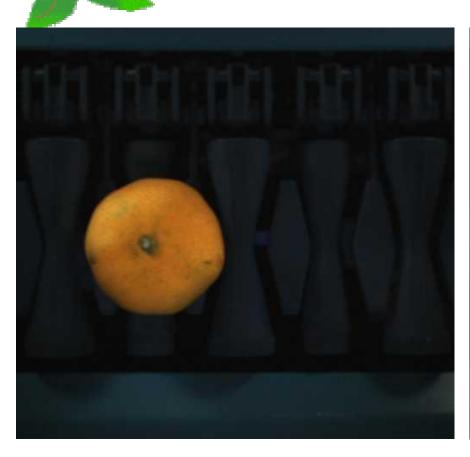
Information from Mobile citrus fruit grading robot

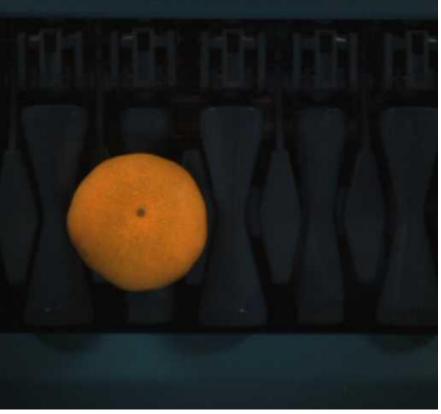
(Fruit location, harvesting time, Fruit appearance, Internal quality, Leaf color, Canopy size, Flower quantity etc.)



Images from inspection cameras

(Fruit appearance: color, shape, size, and defect)







Information from Mobile citrus fruit grading robot

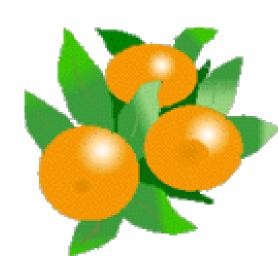
Robot location Harvesting Time

Fruit appearance: color, shape, size, and defect

Internal quality: Sugar content

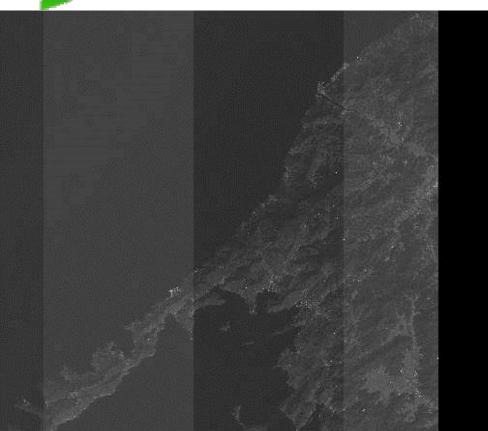
Canopy size (Field-server) Flower quantity (Field-server)

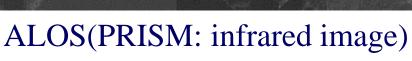
Leaf color (Satellite, Field-server) etc.



Satellite images of citrus production area (Ehime Prefecture, Shikoku, Japan)

Soil temperature, Water content of soil, Leaf color

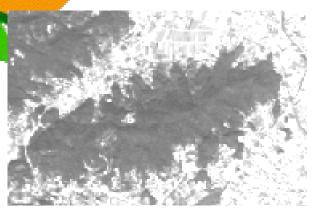




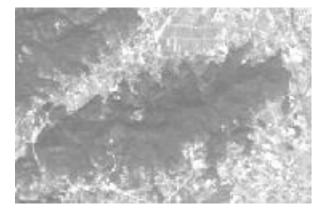


ALOS(AVNIR2:color image)
Courtesy of JAXA

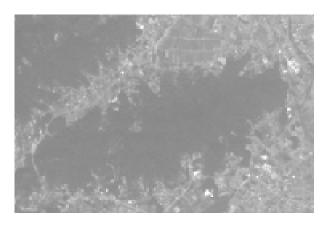
Component images



Red image



Green image

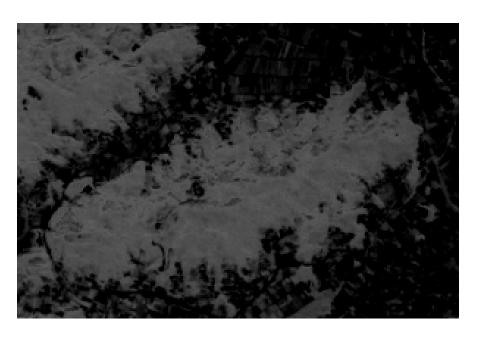


Blue image



Near Infrared image





NDVI (Normalized Difference Vegetation Index)

(near infrared - red)
(near infrared + red)

RVI (Ratio Vegetation Index)

near infrared / red

Information from Satellite

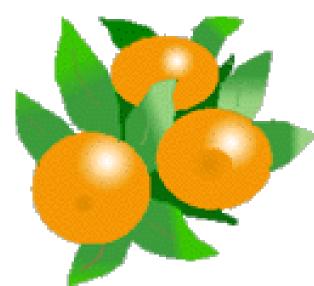
Soil temperature (Field-server)

Water content of soil (Field-server)

Leaf color (Grading robot, Field-server)

Information from Field-server

Temperature, Humidity Soil temperature, Soil water Quantity of sunlight, Precipitation, Wind direction and velocity Leaf color, Flower quantity, Canopy size



Information from Field-server

Temperature

Humidity

Soil temperature (Satellite)

Water content of soil (Satellite)

Quantity of sunlight

Precipitation

Wind direction and velocity

Leaf color (Grading robot, Satellite)

Flower quantity (Grading robot)

Canopy size (Grading robot)

Information from fruit grading facility and operators

Fruit appearance, Internal quality, Farm ID, Fertilization, Irrigation, Operation time and date



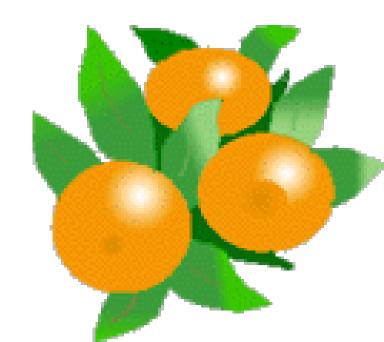


Information from fruit grading facility and operators

Fruit appearance: color, shape, size, and defect

Internal quality: Sugar content

Farm ID
Fertilization
Irrigation
Chemicals
Operation time and date



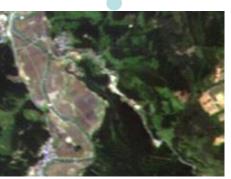
Satellite

Grading robot

Field-server

Grading facility and Operator





Wide-range giography

Environmental info.

JAXA



接作ハンドル 果実投入口 カラーマリング用 カラーマリング用 カラーマカメラ カラーマカメラ カラーマカメラ カラーマカメラ カラーマカメラ ひ・ローラーピンコンペア (RPC) 整列装置 反転機構 超音波 センサ

Product info.





Local climate Info. Environmental info.

Operation record



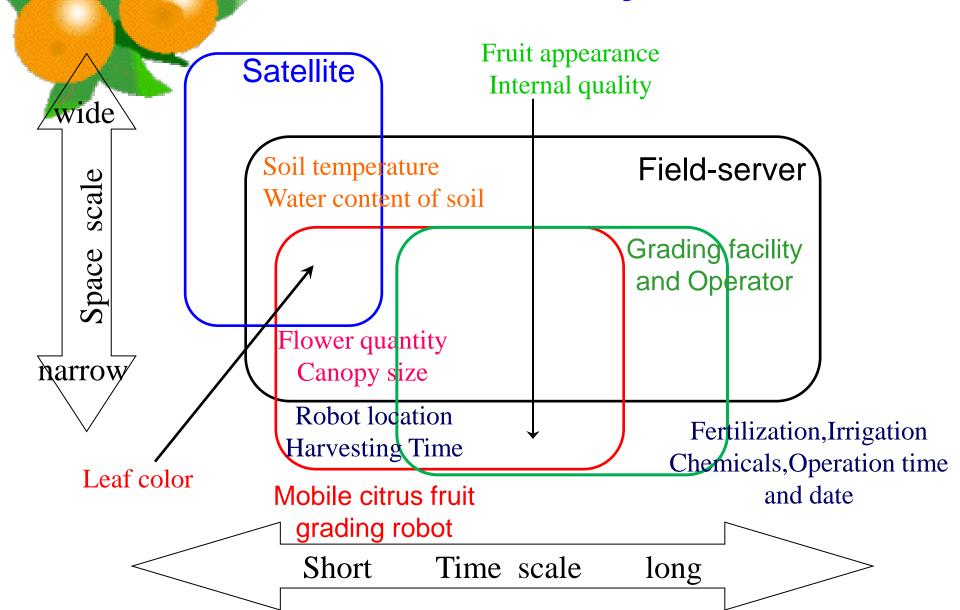






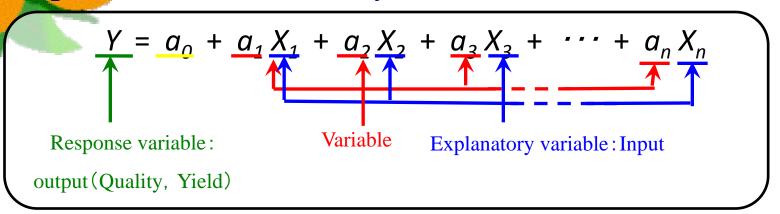
Database

Multi-dimensional analysis of data

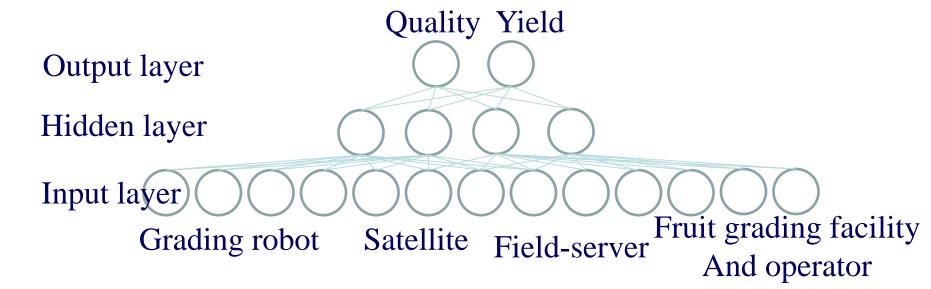


Analysis of relation between input and output data

Multiple classification analysis



Neural network



Our goal

